Design And Implementation Of Model Predictive Control

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Model Predictive Control of High Power Converters and Industrial Drives - Tobias Geyer 2016-09-12

In this original book on model predictive control (MPC) for power electronics, the focus is put on high-power applications with multilevel converters operating at switching frequencies well below 1 kHz, such as medium-voltage drives and modular multi-level converters. Consisting of two main parts, the first offers a detailed review of three-phase power electronics, electrical machines, carrier-based pulse width modulation, optimized pulse patterns, state-of-the art converter control methods and the principle of MPC. The second part is an in-depth treatment of MPC methods that fully exploit the performance potential of high-power converters. These control methods combine the fast control responses of deadbeat control with the optimal steady-state performance of optimized pulse patterns by resolving the antagonism between the two. MPC is expected to evolve into the control method of choice for power

electronic systems operating at low pulse numbers with multiple coupled variables and tight operating constraints it. Model Predictive Control of High Power Converters and Industrial Drives will enable to reader to learn how to increase the power capability of the converter, lower the current distortions, reduce the filter size, achieve very fast transient responses and ensure the reliable operation within safe operating area constraints. Targeted at power electronic practitioners working on control-related aspects as well as control engineers, the material is intuitively accessible, and the mathematical formulations are augmented by illustrations, simple examples and a book companion website featuring animations. Readers benefit from a concise and comprehensive treatment of MPC for industrial power electronics, enabling them to understand, implement and advance the field of high-performance MPC schemes.

Model Predictive Control System Design and Implementation Using MATLAB® - Liuping Wang 2009-02-14

Model Predictive Control System Design and Implementation Using MATLAB® proposes methods for design and implementation of MPC

systems using basis functions that confer the following advantages: - continuous- and discrete-time MPC problems solved in similar design frameworks; - a parsimonious parametric representation of the control trajectory gives rise to computationally efficient algorithms and better on-line performance; and - a more general discrete-time representation of MPC design that becomes identical to the traditional approach for an appropriate choice of parameters. After the theoretical presentation, coverage is given to three industrial applications. The subject of quadratic programming, often associated with the core optimization algorithms of MPC is also introduced and explained. The technical contents of this book is mainly based on advances in MPC using state-space models and basis functions. This volume includes numerous analytical examples and problems and MATLAB® programs and exercises.

Predictive Control - Yugeng Xi 2019-11-12

This book is a comprehensive introduction to model predictive control (MPC), including its basic principles and algorithms, system analysis and design methods, strategy developments and practical applications. The main contents of the

book include an overview of the development trajectory and basic principles of MPC, typical MPC algorithms, quantitative analysis of classical MPC systems, design and tuning methods for MPC parameters, constrained multivariable MPC algorithms and online optimization decomposition methods. Readers will then progress to more advanced topics such as nonlinear MPC and its related algorithms, the diversification development of MPC with respect to control structures and optimization strategies, and robust MPC. Finally, applications of MPC and its generalization to optimization-based dynamic problems other than control will be discussed. Systematically introduces fundamental concepts, basic algorithms, and applications of MPC Includes a comprehensive overview of MPC development, emphasizing recent advances and modern approaches Features numerous MPC models and structures, based on rigorous research Based on the best-selling Chinese edition, which is a key text in China Predictive Control: Fundamentals and Developments is written for advanced undergraduate and graduate students and researchers specializing in control technologies. It is also a useful reference for industry

professionals, engineers, and technicians specializing in advanced optimization control technology.

Nonlinear Model Predictive Control - Frank Allgöwer 2012-12-06

During the past decade model predictive control (MPC), also referred to as receding horizon control or moving horizon control, has become the preferred control strategy for quite a number of industrial processes. There have been many significant advances in this area over the past years, one of the most important ones being its extension to nonlinear systems. This book gives an up-to-date assessment of the current state of the art in the new field of nonlinear model predictive control (NMPC). The main topic areas that appear to be of central importance for NMPC are covered, namely receding horizon control theory, modeling for NMPC, computational aspects of on-line optimization and application issues. The book consists of selected papers presented at the International Symposium on Nonlinear Model Predictive Control – Assessment and Future Directions, which took place from June 3 to 5, 1998, in Ascona, Switzerland. The book is geared towards researchers and

practitioners in the area of control engineering and control theory. It is also suited for postgraduate students as the book contains several overview articles that give a tutorial introduction into the various aspects of nonlinear model predictive control, including systems theory, computations, modeling and applications.

Model Predictive Control - James Blake Rawlings 2009

Economic Model Predictive Control - Matthew Ellis 2016-07-27

This book presents general methods for the design of economic model predictive control (EMPC) systems for broad classes of nonlinear systems that address key theoretical and practical considerations including recursive feasibility, closed-loop stability, closed-loop performance, and computational efficiency. Specifically, the book proposes: Lyapunov-based EMPC methods for nonlinear systems; two-tier EMPC architectures that are highly computationally efficient; and EMPC schemes handling explicitly uncertainty, time-varying cost functions, time-delays and multiple-time-scale dynamics. The proposed methods employ a variety of tools

ranging from nonlinear systems analysis, through Lyapunov-based control techniques to nonlinear dynamic optimization. The applicability and performance of the proposed methods are demonstrated through a number of chemical process examples. The book presents state-of-the-art methods for the design of economic model predictive control systems for chemical processes.In addition to being mathematically rigorous, these methods accommodate key practical issues, for example, direct optimization of process economics, time-varying economic cost functions and computational efficiency. Numerous comments and remarks providing fundamental understanding of the merging of process economics and feedback control into a single framework are included. A control engineer can easily tailor the many detailed examples of industrial relevance given within the text to a specific application. The authors present a rich collection of new research topics and references to significant recent work making Economic Model Predictive Control an important source of information and inspiration for academics and graduate students researching the area and for process engineers interested in applying its ideas.

Receding Horizon Control - Wook Hyun Kwon 2006-03-30

Easy-to-follow learning structure makes absorption of advanced material as pain-free as possible Introduces complete theories for stability and cost monotonicity for constrained and non-linear systems as well as for linear systems In co-ordination with MATLAB® files available from springeronline.com, exercises and examples give the student more practice in the predictive control and filtering techniques presented

Model Predictive Control - Eduardo F. Camacho 2013-01-10

The second edition of "Model Predictive Control" provides a thorough introduction to theoretical and practical aspects of the most commonly used MPC strategies. It bridges the gap between the powerful but often abstract techniques of control researchers and the more empirical approach of practitioners. The book demonstrates that a powerful technique does not always require complex control algorithms. Many new exercises and examples have also been added throughout. Solutions available for download from the authors' website save the tutor time and enable the student to follow results more closely even when

the tutor isn't present.

Advances in Mechanism and Machine Science - Tadeusz Uhl 2019-06-13

This book gathers the proceedings of the 15th IFToMM World Congress, which was held in Krakow, Poland, from June 30 to July 4, 2019. Having been organized every four years since 1965, the Congress represents the world's largest scientific event on mechanism and machine science (MMS). The contributions cover an extremely diverse range of topics, including biomechanical engineering, computational kinematics, design methodologies, dynamics of machinery, multibody dynamics, gearing and transmissions, history of MMS, linkage and mechanical controls, robotics and mechatronics, micro-mechanisms, reliability of machines and mechanisms, rotor dynamics, standardization of terminology, sustainable energy systems, transportation machinery, tribology and vibration. Selected by means of a rigorous international peer-review process, they highlight numerous exciting advances and ideas that will spur novel research directions and foster new multidisciplinary collaborations.

Design and Implementation of Model Predictive

Control Algorithms for Small Satellite Three-axis Stabilization - Chen, Xi 2011

Mixed Integer Nonlinear Programming - Jon Lee 2011-12-02

Many engineering, operations, and scientific applications include a mixture of discrete and continuous decision variables and nonlinear relationships involving the decision variables that have a pronounced effect on the set of feasible and optimal solutions. Mixed-integer nonlinear programming (MINLP) problems combine the numerical difficulties of handling nonlinear functions with the challenge of optimizing in the context of nonconvex functions and discrete variables. MINLP is one of the most flexible modeling paradigms available for optimization; but because its scope is so broad, in the most general cases it is hopelessly intractable. Nonetheless, an expanding body of researchers and practitioners — including chemical engineers, operations researchers, industrial engineers, mechanical engineers, economists, statisticians, computer scientists, operations managers, and mathematical programmers — are interested in solving large-scale MINLP instances.

Model Predictive Control for Doubly-Fed Induction Generators and Three-Phase Power Converters - Alfeu Sguarezi 2022-01-21

Model Predictive Control for Doubly-Fed Induction Generators and Three-Phase Power Converters describes the application of model predictive control techniques with modulator and finite control sets to squirrel cage induction motor and in doubly-fed induction generators using field orientation control techniques as both current control and direct power control. Sections discuss induction machines, their key modulation techniques, introduce the utility of model predictive control, review core concepts of vector control, direct torque control, and direct power control alongside novel approaches of MPC. Mathematical modeling of cited systems, MPC theory, their applications, MPC design and simulation in MATLAB are also considered in-depth. The work concludes by addressing implementation considerations, including generator operation under voltage sags or distorted voltage and inverters connected to the grid operating under distorted voltage. Experimental results are presented in full. Adopts model predictive control design for optimized

induction machines geared for complex grid dynamics Demonstrates how to simulate model predictive control using MATLAB and Simulink Presents information about hardware implementation to obtain experimental results Covers generator operation under voltage sags or distorted voltage

Factories of the Future - Tullio Tolio 2019-02-14 This book is open access under a CC BY 4.0 license.This book presents results relevant in the manufacturing research field, that are mainly aimed at closing the gap between the academic investigation and the industrial application, in collaboration with manufacturing companies. Several hardware and software prototypes represent the key outcome of the scientific contributions that can be grouped into five main areas, representing different perspectives of the factory domain:1) Evolutionary and reconfigurable factories to cope with dynamic production contexts characterized by evolving demand and technologies, products and processes.2) Factories for sustainable production, asking for energy efficiency, low environmental impact products and processes, new de-production logics, sustainable logistics.3) Factories for the

People who need new kinds of interactions between production processes, machines, and human beings to offer a more comfortable and stimulating working environment.4) Factories for customized products that will be more and more tailored to the final user's needs and sold at cost-effective prices.5) High performance factories to yield the due production while minimizing the inefficiencies caused by failures, management problems, maintenance.This books is primarily targeted to academic researchers and industrial practitioners in the manufacturing domain.

Modern Predictive Control - Ding Baocang

2018-10-03

Modern Predictive Control explains how MPC differs from other control methods in its implementation of a control action. Most importantly, MPC provides the flexibility to act while optimizing—which is essential to the solution of many engineering problems in complex plants, where exact modeling is impossible. The superiority of MPC is in its numerical solution. Usually, MPC is employed to solve a finite-horizon optimal control problem at each sampling instant and obtain control actions for both the present time and a future period. However, only

the current control move is applied to the plant. This complete, step-by-step exploration of various approaches to MPC: Introduces basic concepts of systems, modeling, and predictive control, detailing development from classical MPC to synthesis approaches Explores use of Model Algorithmic Control (MAC), Dynamic Matrix Control (DMC), Generalized Predictive Control (GPC), and Two-Step Model Predictive Control Identifies important general approaches to synthesis Discusses open-loop and closed-loop optimization in synthesis approaches Covers output feedback synthesis approaches with and without a finite switching horizon This book gives researchers a variety of models for use with one- and two-step control. The author clearly explains the variations between predictive control methods—and the root of these differences—to illustrate that there is no one ideal MPC and that one should remain open to selecting the best possible model in each unique circumstance.

Model Predictive Control of Wind Energy Conversion Systems - Venkata Yaramasu 2016-12-19

Model Predictive Control of Wind Energy Conversion Systems addresses the predicative

control strategy that has emerged as a promising digital control tool within the field of power electronics, variable-speed motor drives, and energy conversion systems. The authors provide a comprehensive analysis on the model predictive control of power converters employed in a wide variety of variable-speed wind energy conversion systems (WECS). The contents of this book includes an overview of wind energy system configurations, power converters for variable-speed WECS, digital control techniques, MPC, modeling of power converters and wind generators for MPC design. Other topics include the mapping of continuous-time models to discrete-time models by various exact, approximate, and quasi-exact discretization methods, modeling and control of wind turbine grid-side two-level and multilevel voltage source converters. The authors also focus on the MPC of several power converter configurations for full variable-speed permanent magnet synchronous generator based WECS, squirrel-cage induction generator based WECS, and semi-variable-speed doubly fed induction generator based WECS. Furthermore, this book: Analyzes a wide variety of practical WECS, illustrating important concepts

with case studies, simulations, and experimental results Provides a step-by-step design procedure for the development of predictive control schemes for various WECS configurations Describes continuous- and discrete-time modeling of wind generators and power converters, weighting factor selection, discretization methods, and extrapolation techniques Presents useful material for other power electronic applications such as variable-speed motor drives, power quality conditioners, electric vehicles, photovoltaic energy systems, distributed generation, and high-voltage direct current transmission. Explores S-Function Builder programming in MATLAB environment to implement various MPC strategies through the companion website Reflecting the latest technologies in the field, Model Predictive Control of Wind Energy Conversion Systems is a valuable reference for academic researchers, practicing engineers, and other professionals. It can also be used as a textbook for graduate-level and advanced undergraduate courses.

Model-Based Predictive Control - J.A. Rossiter 2003-06-27

Model Predictive Control (MPC) has become a widely used methodology across all engineering

disciplines, yet there are few books which study this approach. Until now, no book has addressed in detail all key issues in the field including apriori stability and robust stability results. Engineers and MPC researchers now have a volume that provides a complete overview of the theory and practice of MPC as it relates to process and control engineering. Model-Based Predictive Control, A Practical Approach, analyzes predictive control from its base mathematical foundation, but delivers the subject matter in a readable, intuitive style. The author writes in layman's terms, avoiding jargon and using a style that relies upon personal insight into practical applications. This detailed introduction to predictive control introduces basic MPC concepts and demonstrates how they are applied in the design and control of systems, experiments, and industrial processes. The text outlines how to model, provide robustness, handle constraints, ensure feasibility, and guarantee stability. It also details options in regard to algorithms, models, and complexity vs. performance issues.

Model Predictive Control - James Blake Rawlings 2017

Model Predictive Control in the Process Industry - Eduardo F. Camacho 2012-12-06

Model Predictive Control is an important technique used in the process control industries. It has developed considerably in the last few years, because it is the most general way of posing the process control problem in the time domain. The Model Predictive Control formulation integrates optimal control, stochastic control, control of processes with dead time, multivariable control and future references. The finite control horizon makes it possible to handle constraints and non linear processes in general which are frequently found in industry. Focusing on implementation issues for Model Predictive Controllers in industry, it fills the gap between the empirical way practitioners use control algorithms and the sometimes abstractly formulated techniques developed by researchers. The text is firmly based on material from lectures given to senior undergraduate and graduate students and articles written by the authors.

Predictive Control of Power Converters and Electrical Drives - Jose Rodriguez 2012-04-09

Describes the general principles and current research into Model Predictive Control (MPC); the

most up-to-date control method for power converters and drives The book starts with an introduction to the subject before the first chapter on classical control methods for power converters and drives. This covers classical converter control methods and classical electrical drives control methods. The next chapter on Model predictive control first looks at predictive control methods for power converters and drives and presents the basic principles of MPC. It then looks at MPC for power electronics and drives. The third chapter is on predictive control applied to power converters. It discusses: control of a three-phase inverter; control of a neutral point clamped inverter; control of an active front end rectifier, and; control of a matrix converter. In the middle of the book there is Chapter four - Predictive control applied to motor drives. This section analyses predictive torque control of industrial machines and predictive control of permanent magnet synchronous motors. Design and implementation issues of model predictive control is the subject of the final chapter. The following topics are described in detail: cost function selection; weighting factors design; delay compensation; effect of model errors, and prediction of future

references. While there are hundreds of books teaching control of electrical energy using pulse width modulation, this will be the very first book published in this new topic. Unique in presenting a completely new theoretic solution to control electric power in a simple way Discusses the application of predictive control in motor drives, with several examples and case studies Matlab is included on a complementary website so the reader can run their own simulations

Model Predictive Control on Open Water Systems - Peter-Jules van Overloop 2006

"In the research Model Predictive Control on Open Water Systems, the relatively new control methodology Model Predictive Control is configured for application of water quantity control on open water systems, especially on irrigation canals and large drainage systems. The methodology applies an internal model of the open water system, by which optimal control actions are calculated over a prediction horizon. As internal model, two simplified models are used, the Integrator Delay model and the Saint Venant model. Kalman filtering is applied to initialize the internal models. The optimization uses an objective function in which conflicting

objectives can be weighed. In most of the cases, these conflicting objectives are keeping the water levels at different locations in the water system within a range around setpoint and executing this by using as little control effort or energy as possible. To tune the weight factors in the objective function, an estimate of the maximum allowed value of each variable in the objective function is used. The optimization takes the constraints of the control structures into account. Every control time step, the optimal control actions are calculated, while only the first set of control actions is actually executed. This results in a controlled water system that is constantly maintaining the objective in an optimal way, while taking predictions, such as expected irrigation demands or extreme storm events and the constraints of the water system into account."

Practical Design and Application of Model Predictive Control - Nassim Khaled 2018-05-04

Practical Design and Application of Model Predictive Control is a self-learning resource on how to design, tune and deploy an MPC using MATLAB® and Simulink®. This reference is one of the most detailed publications on how to design and tune MPC controllers. Examples

presented range from double-Mass spring system, ship heading and speed control, robustness analysis through Monte-Carlo simulations, photovoltaic optimal control, and energy management of power-split and air-handling control. Readers will also learn how to embed the designed MPC controller in a real-time platform such as Arduino®. The selected problems are nonlinear and challenging, and thus serve as an excellent experimental, dynamic system to show the reader the capability of MPC. The step-by-step solutions of the problems are thoroughly documented to allow the reader to easily replicate the results. Furthermore, the MATLAB® and Simulink® codes for the solutions are available for free download. Readers can connect with the authors through the dedicated website which includes additional free resources at www.practicalmpc.com. Illustrates how to design, tune and deploy MPC for projects in a quick manner Demonstrates a variety of applications that are solved using MATLAB® and Simulink® Bridges the gap in providing a number of realistic problems with very hands-on training Provides MATLAB® and Simulink® code solutions. This includes nonlinear plant models

that the reader can use for other projects and research work Presents application problems with solutions to help reinforce the information learned

Advanced Model Predictive Control - Tao Zheng 2011-07-05

Model Predictive Control (MPC) refers to a class of control algorithms in which a dynamic process model is used to predict and optimize process performance. From lower request of modeling accuracy and robustness to complicated process plants, MPC has been widely accepted in many practical fields. As the guide for researchers and engineers all over the world concerned with the latest developments of MPC, the purpose of "Advanced Model Predictive Control" is to show the readers the recent achievements in this area. The first part of this exciting book will help you comprehend the frontiers in theoretical research of MPC, such as Fast MPC, Nonlinear MPC, Distributed MPC, Multi-Dimensional MPC and Fuzzy-Neural MPC. In the second part, several excellent applications of MPC in modern industry are proposed and efficient commercial software for MPC is introduced. Because of its special industrial origin, we believe that MPC will remain energetic in the future.

Predictive Control of Power Converters and Electrical Drives - Jose Rodriguez 2012-04-30 Describes the general principles and current research into Model Predictive Control (MPC); the most up-to-date control method for power converters and drives The book starts with an introduction to the subject before the first chapter on classical control methods for power converters and drives. This covers classical converter control methods and classical electrical drives control methods. The next chapter on Model predictive control first looks at predictive control methods for power converters and drives and presents the basic principles of MPC. It then looks at MPC for power electronics and drives. The third chapter is on predictive control applied to power converters. It discusses: control of a three-phase inverter; control of a neutral point clamped inverter; control of an active front end rectifier, and; control of a matrix converter. In the middle of the book there is Chapter four - Predictive control applied to motor drives. This section analyses predictive torque control of industrial machines and predictive control of permanent magnet synchronous motors. Design and implementation issues of model predictive control is the subject of

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Control, A Practical Approach, analyzes predictive control from its base mathematical foundation, but delivers the subject matter in a readable, intuitive style. The author writes in layman's terms, avoiding jargon and using a style that relies upon personal insight into practical applications. This detailed introduction to predictive control introduces basic MPC concepts and demonstrates how they are applied in the design and control of systems, experiments, and industrial processes. The text outlines how to model, provide robustness, handle constraints, ensure feasibility, and guarantee stability. It also details options in regard to algorithms, models, and complexity vs. performance issues.

Advanced Model Predictive Control for Autonomous Marine Vehicles - Yang Shi 2023-02-13

This book provides a comprehensive overview of marine control system design related to underwater robotics applications. In particular, it presents novel optimization-based model predictive control strategies to solve control problems appearing in autonomous underwater vehicle applications. These novel approaches bring unique features, such as constraint

handling, prioritization between multiple design objectives, optimal control performance, and robustness against disturbances and uncertainties, into the control system design. They therefore form a more general framework to design marine control systems and can be widely applied. Advanced Model Predictive Control for Autonomous Marine Vehicles balances theoretical rigor – providing thorough analysis and developing provably-correct design conditions – and application perspectives – addressing practical system constraints and implementation issues. Starting with a fixed-point positioning problem for a single vehicle and progressing to the trajectory-tracking and path-following problem of the vehicle, and then to the coordination control of a large-scale multi-robot team, this book addresses the motion control problems, increasing their level of challenge step-by-step. At each step, related subproblems such as path planning, thrust allocation, collision avoidance, and time constraints for real-time implementation are also discussed with solutions. In each chapter of this book, compact and illustrative examples are provided to demonstrate the design and implementation procedures. As a result, this book

is useful for both theoretical study and practical engineering design, and the tools provided in the book are readily applicable for real-world implementation.

Incremental Model Predictive Control System Design and Implementation Using MATLAB/Simulink - Xin Lin 2013

The integral and model predictive controller (MPC) drive controlled outputs to their desired targets, and this thesis addresses the problem of integral controller, incremental and integral MPC when tracking the constant or inconstant references. Design and implementation of the MPC under MATLAB/Simulink environment are discussed both in incremental and integral form. Also one CSTR example is presented to compare the control performances among different integral controller and MPCs.

Towards a Co-design Implementation of a System for Model Predictive Control - Panagiotis Vouzis 2005

Handbook of Model Predictive Control - Saša V. Rakovi 2018-09-01

Recent developments in model-predictive control promise remarkable opportunities for designing

multi-input, multi-output control systems and improving the control of single-input, single-output systems. This volume provides a definitive survey of the latest model-predictive control methods available to engineers and scientists today. The initial set of chapters present various methods for managing uncertainty in systems, including stochastic model-predictive control. With the advent of affordable and fast computation, control engineers now need to think about using "computationally intensive controls," so the second part of this book addresses the solution of optimization problems in "real" time for model-predictive control. The theory and applications of control theory often influence each other, so the last section of Handbook of Model Predictive Control rounds out the book with representative applications to automobiles, healthcare, robotics, and finance. The chapters in this volume will be useful to working engineers, scientists, and mathematicians, as well as students and faculty interested in the progression of control theory. Future developments in MPC will no doubt build from concepts demonstrated in this book and anyone with an interest in MPC will find fruitful information and suggestions for additional

reading.

PID and Predictive Control of Electrical Drives and Power Converters using MATLAB / Simulink - Liuping Wang 2015-03-02

A timely introduction to current research on PID and predictive control by one of the leading authors on the subject PID and Predictive Control of Electric Drives and Power Supplies using MATLAB/Simulink examines the classical control system strategies, such as PID control, feed-forward control and cascade control, which are widely used in current practice. The authors share their experiences in actual design and implementation of the control systems on laboratory test-beds, taking the reader from the fundamentals through to more sophisticated design and analysis. The book contains sections on closed-loop performance analysis in both frequency domain and time domain, presented to help the designer in selection of controller parameters and validation of the control system. Continuous-time model predictive control systems are designed for the drives and power supplies, and operational constraints are imposed in the design. Discrete-time model predictive control systems are designed based on the discretization

of the physical models, which will appeal to readers who are more familiar with sampled-data control system. Soft sensors and observers will be discussed for low cost implementation. Resonant control of the electric drives and power supply will be discussed to deal with the problems of bias in sensors and unbalanced three phase AC currents. Brings together both classical control systems and predictive control systems in a logical style from introductory through to advanced levels Demonstrates how simulation and experimental results are used to support theoretical analysis and the proposed design algorithms MATLAB and Simulink tutorials are given in each chapter to show the readers how to take the theory to applications. Includes MATLAB and Simulink software using xPC Target for teaching purposes A companion website is available Researchers and industrial engineers; and graduate students on electrical engineering courses will find this a valuable resource.

2021 International Conference on Electrical Drives and Power Electronics (EDPE) - IEEE Staff 2021-09-22

The EDPE conference series brings opportunity for engineers, specialists in industry and

academia to create forum for sharing knowledge and exchange experiences on recent development, applications and future trends in all aspects of power electronic systems, electrical machines, electrical drives and their industrial applications

Advanced Model Predictive Control - Tao Zheng 2011-07-05

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for MPC is introduced. Because of its special industrial origin, we believe that MPC will remain energetic in the future.

Constrained Optimal Control of Linear and Hybrid Systems - Francesco Borrelli 2003-09-04

Many practical control problems are dominated by characteristics such as state, input and operational constraints, alternations between different operating regimes, and the interaction of continuous-time and discrete event systems. At present no methodology is available to design controllers in a systematic manner for such systems. This book introduces a new design theory for controllers for such constrained and switching dynamical systems and leads to algorithms that systematically solve control synthesis problems. The first part is a self-contained introduction to multiparametric programming, which is the main technique used to study and compute state feedback optimal control laws. The book's main objective is to derive properties of the state feedback solution, as well as to obtain algorithms to compute it efficiently. The focus is on constrained linear systems and constrained linear hybrid systems. The applicability of the theory is demonstrated

through two experimental case studies: a mechanical laboratory process and a traction control system developed jointly with the Ford Motor Company in Michigan.

Model Predictive Control System Design and Implementation Using MATLAB® - Liuping Wang 2009-03-04

Model Predictive Control System Design and Implementation Using MATLAB® proposes methods for design and implementation of MPC systems using basis functions that confer the following advantages: - continuous- and discrete-time MPC problems solved in similar design frameworks; - a parsimonious parametric representation of the control trajectory gives rise to computationally efficient algorithms and better on-line performance; and - a more general discrete-time representation of MPC design that becomes identical to the traditional approach for an appropriate choice of parameters. After the theoretical presentation, coverage is given to three industrial applications. The subject of quadratic programming, often associated with the core optimization algorithms of MPC is also introduced and explained. The technical contents of this book is mainly based on advances in MPC

using state-space models and basis functions. This volume includes numerous analytical examples and problems and MATLAB® programs and exercises.

New Directions on Model Predictive Control - Jinfeng Liu 2019-01-16

This book is a printed edition of the Special Issue "New Directions on Model Predictive Control" that was published in Mathematics

PID and Predictive Control of Electrical Drives and Power Converters using MATLAB / Simulink - Liuping Wang 2014-12-17

A timely introduction to current research on PID andpredictive control by one of the leading authors on thesubject PID and Predictive Control of Electric Drives and PowerSupplies using MATLAB/Simulink examines the classical controlsystem strategies, such as PID control, feed-forward control andcascade control, which are widely used in current practice. The authors share their experiences in actual design andimplementation of the control systems on laboratory test-beds,taking the reader from the fundamentals through to moresophisticated design and analysis. The bookcontains sections on closed-loop performance analysis in

bothfrequency domain and time domain, presented to help the designer inselection of controller parameters and validation of the controlsystem. Continuous-time model predictive control systems aredesigned for the drives and power supplies, and operationalconstraints are imposed in the design. Discrete-time model predictive control systems are designed basedon the discretization of the physical models, which will appeal toreaders who are more familiar with sampled-data control system.Soft sensors and observers will be discussed for low costimplementation. Resonant control of the electric drives andpower supply will be discussed to deal with the problems of bias insensors and unbalanced three phase AC currents. Brings together both classical control systems and predictivecontrol systems in a logical style from introductory through toadvanced levels Demonstrates how simulation and experimental results are usedto support theoretical analysis and the proposed designalgorithms MATLAB and Simulink tutorials are given in each chapter to showthe readers how to take the theory to applications. Includes MATLAB and Simulink software using xPC Target forteaching purposes

A companion website is available Researchers and industrial engineers; and graduate students onelectrical engineering courses will find this a valuableresource.

Virtual Inertia Synthesis and Control - Thongchart Kerdphol 2020-11-28

This book provides a thorough understanding of the basic principles, synthesis, analysis, and control of virtual inertia systems. It uses the latest technical tools to mitigate power system stability and control problems under the presence of high distributed generators (DGs) and renewable energy sources (RESs) penetration. This book uses a simple virtual inertia control structure based on the frequency response model, complemented with various control methods and algorithms to achieve an adaptive virtual inertia control respect to the frequency stability and control issues. The chapters capture the important aspects in virtual inertia synthesis and control with the objective of solving the stability and control problems regarding the changes of system inertia caused by the integration of DGs/RESs. Different topics on the synthesis and application of virtual inertia are thoroughly covered with the description and analysis of

numerous conventional and modern control methods for enhancing the full spectrum of power system stability and control. Filled with illustrative examples, this book gives the necessary fundamentals and insight into practical aspects. This book stimulates further research and offers practical solutions to real-world power system stability and control problems with respect to the system inertia variation triggered by the integration of RESs/DGs. It will be of use to engineers, academic researchers, and university students interested in power systems dynamics, analysis, stability and control.

Frontiers of Model Predictive Control - Tao Zheng 2012-02-24

Model Predictive Control (MPC) usually refers to a class of control algorithms in which a dynamic process model is used to predict and optimize process performance, but it is can also be seen as a term denoting a natural control strategy that matches the human thought form most closely. Half a century after its birth, it has been widely accepted in many engineering fields and has brought much benefit to us. The purpose of the book is to show the recent advancements of MPC to the readers, both in theory and in engineering.

The idea was to offer guidance to researchers and engineers who are interested in the frontiers of MPC. The examples provided in the first part of this exciting collection will help you comprehend some typical boundaries in theoretical research of MPC. In the second part of the book, some excellent applications of MPC in modern engineering field are presented. With the rapid development of modeling and computational technology, we believe that MPC will remain as energetic in the future.

Predictive Control for Linear and Hybrid Systems - Francesco Borrelli 2017-06-22

Model Predictive Control (MPC), the dominant advanced control approach in industry over the past twenty-five years, is presented comprehensively in this unique book. With a simple, unified approach, and with attention to real-time implementation, it covers predictive control theory including the stability, feasibility, and robustness of MPC controllers. The theory of explicit MPC, where the nonlinear optimal feedback controller can be calculated efficiently, is presented in the context of linear systems with linear constraints, switched linear systems, and, more generally, linear hybrid systems. Drawing

upon years of practical experience and using numerous examples and illustrative applications, the authors discuss the techniques required to design predictive control laws, including algorithms for polyhedral manipulations, mathematical and multiparametric programming and how to validate the theoretical properties and to implement predictive control policies. The most important algorithms feature in an accompanying free online MATLAB toolbox, which allows easy access to sample solutions. Predictive Control for Linear and Hybrid Systems is an ideal reference for graduate, postgraduate and advanced control practitioners interested in theory and/or implementation aspects of predictive control.

Explicit Nonlinear Model Predictive Control - Alexandra Grancharova 2012-03-22

Nonlinear Model Predictive Control (NMPC) has become the accepted methodology to solve complex control problems related to process industries. The main motivation behind explicit NMPC is that an explicit state feedback law avoids the need for executing a numerical optimization algorithm in real time. The benefits of an explicit solution, in addition to the efficient on-line computations, include also verifiability of the

implementation and the possibility to design embedded control systems with low software and hardware complexity. This book considers the multi-parametric Nonlinear Programming (mp-NLP) approaches to explicit approximate NMPC of constrained nonlinear systems, developed by the authors, as well as their applications to various NMPC problem formulations and several case studies. The following types of nonlinear systems are considered, resulting in different NMPC problem formulations: Nonlinear systems described by first-principles models and nonlinear systems described by black-box models; - Nonlinear systems with continuous control inputs and nonlinear systems with quantized control inputs; - Nonlinear systems without uncertainty and nonlinear systems with uncertainties (polyhedral description of uncertainty and stochastic description of uncertainty); - Nonlinear systems, consisting of interconnected nonlinear sub-systems. The proposed mp-NLP approaches are illustrated with applications to several case studies, which are taken from diverse areas such as automotive mechatronics, compressor control, combustion plant control, reactor control, pH maintaining system control,

cart and spring system control, and diving computers.

Distributed Model Predictive Control for Plant-Wide Systems - Shaoyuan Li 2017-05-02

A comprehensive examination of DMPC theory and its technological applications • A comprehensive examination of DMPC theory and its technological applications from basic through to advanced level • A systematic introduction to DMPC technology providing classic DMPC coordination strategies, analysis of their performance, and design methods for both unconstraint and constraint systems • Includes the system partition methods, coordination strategies, the performance analysis and how to design stabilized DMPC under different coordination strategies • Presents useful theories and technologies which can be used in many different industrial fields, such as the metallurgical process and high speed transport, helping readers to grasp the procedure of using the DMPC • Reflects the authors' combined research in the area, providing a wealth of and current and background information